

Abstract

Iman Gamal Morsi

Investigation of Collision Avoidance and Localization in WSNs

The most important two problems in Wireless Sensor Network (WSN) is localization and collision avoidance of the transferred packets. A solution for these obstacles is introduced in this work. Localization is solved by upgrading anchor position accuracy using a global positioning system (GPS); position estimates. Collision avoidance obstacle is discussed in the simulation of WSN; studying the effect of collision occurrence during communication between wireless sensor nodes.